



Global Leading Provider of Collaborative & Industrial Robot Arm Solutions

DOBOT
Shake Hands With The Future

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CONTROL SYSTEM

SC Series Integrated Robot Controller CR5 Collaborative Robot Controller Teach Pendant DOBOT SCStudio

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COMPANY PROFILE





GLOBAL LEADING PROVIDER OF COLLABORATIVE & INDUSTRIAL ROBOT ARM SOLUTIONS

About DOBOT

Founded in July 2015, Shenzhen Yuejiang Technology Co., Ltd. (DOBOT) is a global leading provider of collaborative and industrial robot arm solutions. To date, DOBOT has established itself as China's No.1 exporter of industrial robots in 2018 and 2019, celebrating 200,000 educational and industrial users all over the world. DOBOT was named as the Top 80 Artificial Intelligence Companies by Hurun Report in 2018.

DOBOT Team

DOBOT is a team of more than 300 employees, 60% of which are dedicated to ongoing R&D. DOBOT team consists of experts in algorithms, mechanical design, servo systems, robotics and industrial automation. Core members of DOBOT have all studied or worked at the world-prestigious universities and companies, such as Tsinghua University, University of Bremen and University of Melbourne, MIT, ABB and Huawei.

R&D

Since 2015, we have achieved technical breakthroughs in stepper motor driver and servo motor driver, and acquired 130 intellectual property rights and 72 software copyrights both domestically and internationally.

Accredited as a National High-Tech Enterprise, DOBOT adheres to independent innovation and has been certified by ISO9001 quality management system, ISO14001 environmental management system and GB/T29490 intellectual property management system.

Dobot Partners & Customers



Awards & Honors

Dobot's new-generation intelligent robot arms won many international-acclaimed awards: the CES 2018 Innovation Award, the 2018 Red Dot Award, the 2018 iF Design Award, the K-Design 2019, the Red Star Design Award 2019 and the 2020 Red Dot Award.

DOBOT Highlights

In recognition of the excellence of our robot arms, DOBOT was invited to present our solutions at the Google I/O 2017, Chevrolet Gala Night 2017 and PyeongChang 2018 Olympic Winter Games and has become an AI Partner of HUAWEI CLOUD in 2020. We enjoy premium market position thanks to our own hard work and for being trusted by our customers from all over the world, including Fortune 500 companies like Volkswagen, Toyota, OMRON, SONY, Tencent Cloud and Alibaba.



Shake Hands With The Future

DOBOT CR5 Cost-Effective Collaborative 6-Axis Robot Arm

y to program, DOBOT CR5 is cost-effective, ation easier than ever dly and fast to set ur





Easy to Use

Can be controlled via visual programming on mobile phone or tablet through Wi-Fi connection; support hand-held teaching

Inherently Safe & Collision-Free, Collaborative

Offer multiple protection methods:

Flexible & Fast Deployment

Cost-Effective & Durable

Work with mainstream end-effectors and accessories

No security fence required, 32,000 hours of service life, builtin energy feedback & hectowatt-level power consumption ·

camera entry detection

• 10cm-proximity pre-touch sensing & online route planning (when equiped with electronic skin)



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Pick and

Place

3C Industry

Research

Machine Assembly Dispensing Tending



σМ <u>____</u>



Visual Screwdriving Inspection Industries









Aerospace



Automotive











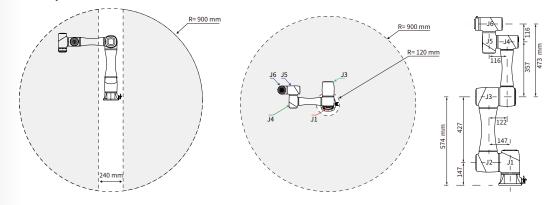
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Technical Parameters

Weight	23kg	
Payload	5kg	
Reach	900mm	
Maximum Speed of TCP	3m/s	
	J1	±360°
	J2	±360°
	J3	±160°
Joint Ranges	J4	±360°
	J5	±360°
	J6	±360°
	J1	180°/s
	J2	180°/s
Leint Meuineur Connel	J3	180°/s
Joint Maximum Speed	J4	180°/s
	J5	180°/s
	JG	180°/s
	Digital Input	2
	Digital Output	2
End-effector I/O Interface	Analog Input	2
	Analog Output	0
	Digital Input	16
Controller I/O interface	Digital Input/DigitalOutput	16
Controller I/O Interface	Analog Input	2
	Analog Output	2
Repeatability	±0.03mm	
Power	100V~240V AC, 50~60Hz	
Communication Interface	RS485(End-Effector), TCP/IP, Modbus, EtherCAT, Wi-Fi	
IP Classification	IP54	
Temperature	0°C ~45°C	
Power Supply	400W	
Material	Aluminum alloy, ABS	



Workspace



Compatible Effectors & Accessories







DH Robotics AG-95

Robotiq 2F-85

SCHUNK CO-ACT EGP-C

Vision







Microscan MicroHawk MV-40

/IV-40 In-Sight 700

In-Sight 7000 Series Vision Systems

Hikrobot MV-SC2016M

Force Torque Sensor





OnRobot HEX-H



FT 300

Lin

LinkTouch Wrist

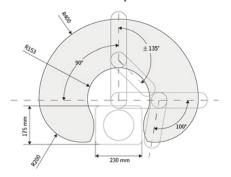
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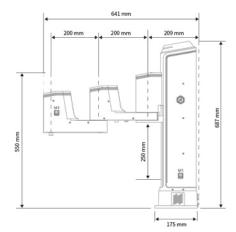
Technical Parameters

Reach	400mm			
Rated Payload		1.5kg		
	Туре	Mechanica limitatior		Software limitation
	Rear arm	-90° ~90°		-85° ~85°
Maximum magnitude	Forearm	-135° ~135	ō°	-135° ~135°
	Z-axis screw	0mm~250n	۱m	10mm- 235mm
	End-effector rotation	unlimited	ł	-360° ~360°
	Joint speed of Rear			180°/s
Maximum speed	Resultant s Forearm an	peed of the d Rear Arm		2000 mm/s
	Speed o	of Z Axis		1000 mm/s
Repeatability		0.02mr	n	
Power	Power A	dapter: 100V-2 Dobot M1: 4		
Communication interface		Ethernet、R	S-232	С
I/O	22 digital out	tputs, 24 digita	linpu	its, 6 ADC inputs
Software		M1 Stud	lio	
System		Linux		





Overall Dimensions



DOBOT M1 Collaborative SCARA Robot Arm

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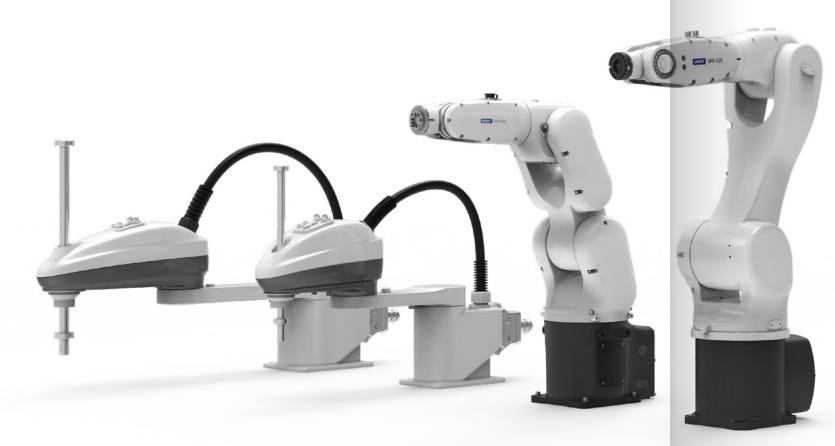
DOBOT M1 is the world's first collaborative SCARA robot arm for small and medium-sized factories. Lightweight and portable, the 4-axis robot arm delivers fast setup and flexible deployment. M1's effective cost, easy programming and low maintenance make it a perfect automation solution for SMEs.

Application Scenarios

💋 ДОВОТ

Pick & place, screwdriving, dispensing, palletizing, machine tending, visual inspection

DOBOT SA & SR INDUSTRIAL ROBOT SERIES





LIGHTWEIGHT ALL-PERCEPTIVE INDUSTRIAL ROBOT ARM

DOBOT SA & SR Industrial Robot Series consist of 4-axis and 6-axis lightweight industrial robot arms that are independently developed by DOBOT. These two series are characterized by the integrated drive and controlling system, light compact body and small footprint, outperforming the existing industrial robots. With high precision, fast moving speed and simple deployment, the series is perfectly suitable for flexible production lines with limited working space and can meet the needs of precise assembly, inspecting, transporting, loading and unloading, etc., greatly improving production efficiency.

Fully Self-Developed, Outstanding Performance

Equipped with 100% self-developed encoders, controllers and drivers, DOBOT SR Robots have achieved brilliant breakthroughs in main technological areas including vision, control, drivers and robotic body, featuring outstanding performance thanks to its core technology of fourin-one servo driver.

All-Perceptive Man-Machine Collaboration

Combining identification of full-parameter dynamic model, autoadaption of parameters and estimation of external force on the payload, DOBOT SR Robots realize force perception, collision detection, intelligent picking and hand-held teaching with 2D and 3D visual aids.

Optimal Dynamic Control, Faster, More Precise and More Endurable

As the dynamic feedforward keeps stable trajectory and optimal operating time, the robot arm can automatically run on the best accelerating and decelerating parameters. Controlled and constrained by torque, both high speed and long operating life of the whole machine are fairly ensured.

Lightweight Integration & Quick Deployment

Featuring lightweight and compact design, integrated driver and controller, the small-size DOBOT SR robot is easy to move. Simple and flexible deployment makes it possible to quickly switch operations without changing the layout of the production line.

Simplified Industrial Vision Applications

One-button auto-calibration, tool compensation and rectification enable the robot arm to be used for vision applications, fast deployment of which can be realized when combined with a vision kit.



DOBOT 4-AXIS INDUSTRIAL ROBOT SERIES

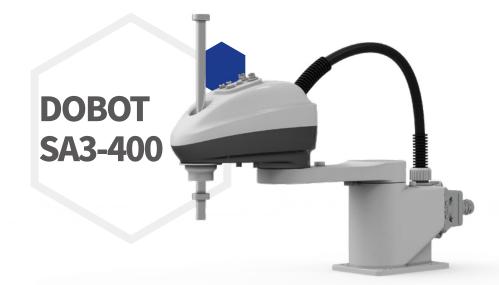
The professional design enables DOBOT 4 Axis Industrial Robot Series to have stronger rigidity and higher reliability. Featuring high speed, high precision, high performance, and easy installation, operation and maintenance, the cost-effective robot arms can greatly improve the adaptability for performing complex assembling tasks.

Product Features

- Optimal dynamic time control, auto-operation at the perfect accelerating and decelerating parameters
 Trajectory stays the same at both high and low speed, what you see is what you get
- 3. Vision kit enables high-accuracy vision applications

Application Scenarios

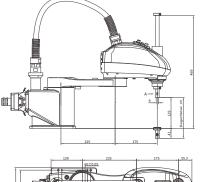


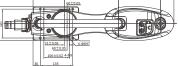


Technical Parameters

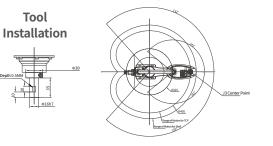
Reach	4	00mm
Devide and	Rated Load	1kg
Payload	Maximum	3kg
Standard Cycle Time	().415s
	J1+J2	±0.01mm
Position Repeatability	J3	±0.01mm
	J4	±0.01°
	J1	±132°
Mation Danga	J2	±141°
Motion Range	J3	170mm
	J4	±360°
	J1	720° /s
	J2	720°/s
Maximum Speed	J1+J2(resultant velocity)	7200mm/s
	J3	1000mm/s
	J4	2500°/s
	J1	400W
Motor Power	J2	100W
MOLOI FOWEI	J3	100W
	J4	100W
I/O Interface	-2-channel relay output -28-channel digital input -17-channel digital output -6-channel Rob IO digital input -4-channel Rob DO digital output -2-channel external ABZ	
User Air Pipe	ф	Smm x 2
Net Weight		13kg
Communication Mode	Ethernet, Modbus	
Internal PLC	Support	
External Axis Control	Support	
Working Environment	Temperature: 5°C ~40°C Humidity: 10%~80%, no condensation	
Mounting Type	Desk	

Overall Dimensions





Workspace

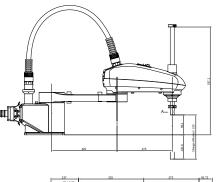


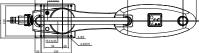


Technical Parameters

Reach	600mm	
Delast	Rated Load	Зkg
Payload	Maximum	бкд
Standard Cycle Time		0.47s
Position	J1+J2	±0.02mm
Repeatability	J3	±0.01mm
Repeatability	J4	±0.01°
	J1	±132°
	J2	±145°
Motion Range	J3	220mm
	J4	±360°
	J1	450° /s
	J2	720°/s
Maximum Speed	J1+J2(resultant velocity)	8100mm/s
	J3	1000mm/s
]4	2000° /s
	J1	400W
Mala Di	J2	200W
Motor Power	J3	100W
	J4	100W
I/O Interface	 -2-channel relay output -28-channel digital input -17-channel digital output -6-channel Rob IO digital input -4-channel Rob DO digital output -2-channel external ABZ 	
User Air Pipe	ф6mm x 2	
Net Weight		17kg
Communication Mode	Ethernet, Modbus	
Internal PLC	Support	
External Axis Control	Support	
Working Environment	Temperature: 5°C ~40°C Humidity: 10%~80%, no condensation	
Mounting Type	Desk	

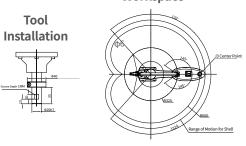
Overall Dimensions





Tool

Workspace



DOBOT 6-AXIS INDUSTRIAL ROBOT SERIES

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Equipped with a great servo control system and high-precision driver-integrated technology, DOBOT 6-axis robot makes fast, flexible and agile movement at high precision with excellent dynamic payload performance. Smooth running track, simple and smooth control, and light & compact design makes it capable of assembly line operations without any pressure.

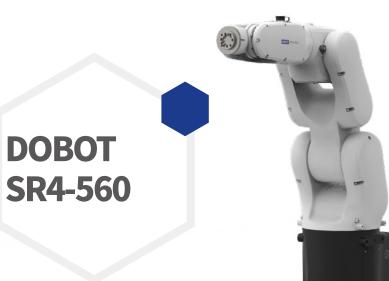
Product Features

- 1. Easy-to-move integrated driver & controller and quick & flexible employment
- 2. Dynamic torque control, faster, more stable and more endurable
- 3. Advanced dynamic trajectory & Smooth controlling experience
- 4. User guided palletizing kit

Application Scenarios



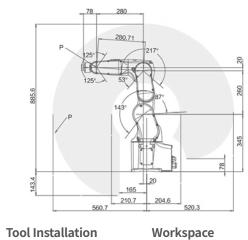


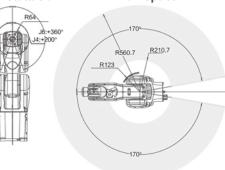


Technical Parameters

Reach		560.7mm
Payload	Rated Load	2kg
,	Maximum	4kg
Position Repeatability		±0.02mm
	J1	±170°
	J2	-143° ~ 87°
Motion Range	J3	-53° ~ 217°
Modorritange]4	±200°
	J5	±125°
	J6	±360°
]1	416°/s
	J2	416° /s
	J3	462° /s
Maximum Speed	J4	560°/s
	J5	560°/s
	JG	740° /s
]1	400W
	J2	400W
Motor Power	J3	200W
WOLDI POWEI	J4	50W
	J5	50W
	JG	50W
I/O Interface	 5 relay outputs 16 digital outputs 24 digital inputs 2 analog outputs (0V-10V, 4mA-20mA) 4 analog inputs (0V-10V, 4mA-20mA) 	
User Circuit		8 in / out
User Air Pipe		φ4mm x 4
Net Weight	26kg	
Communication Mode	Ethernet, Modbus	
Internal PLC	Support	
External Axis Control	Support	
Working Environment	Temperature: 0°C ~45°C Humidity: 10%~80%, no condensation	
Mounting Type		Desk

Overall Dimensions



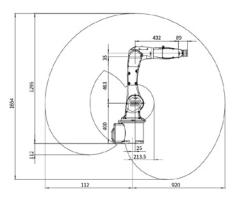




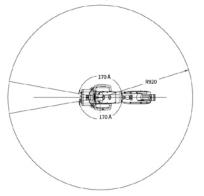
Technical Parameters

Reach	920mm		
Delevi	Rated Load	-	
Payload	Maximum	6kg	
Position Repeatability	:	±0.02mm	
	J1	-170° ~170°	
	J2	-100° ~135°	
Motion Range	J3	-120° ~156°	
wooonnange	J4	-200° ~200°	
	J5	-135° ~135°	
	J6	-360° ~360°	
	J1	380° /s	
	J2	325° /s	
	J3	390° /s	
Maximum Speed	J4	480° /s	
	J5	550° /s	
	J6	800° /s	
	J1	750W	
	J2	750W	
Motor Power	J3	400W	
WOLDI POWEI	J4	100W	
	J5	100W	
	J6	100W	
I/O Interface		uts	
User Circuit		-	
User Air Pipe		-	
Net Weight		47kg	
Communication Mode	Ethernet、Modbus		
Internal PLC	Support		
External Axis Control	Support		
Working Environment	Temperature: 0°C ~45°C Humidity: 20%~80%, no condensation		
Mounting Type	Desk		

Operating Space Diagram







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CONTROL SYSTEM



Driver-Integrated Controller Solution

Combining man-machine interaction, controller and driver, the one-stop solution is tailored for industrial robots, and can quickly adapt to various robot models including SCARA, six-joint, DETLA.

Four-In-One Servo Driver Solution

Equipped with four-in-one servo driver, the controller satisfies different servo requirements of users with support of encoders from Panasonic, Tamagawa, BISS and Nikon.

Minimum Size & Quick Employment

The size of the super compact controller is 400*360*180mm, only 20% of traditional robot controllers' and similar to a computer main cabinet. Just plug and use, easy to move.

Modular & Expandable

EtherCAT networking, modular design, easy extension of external axes, I/O ports, abundant interface resources, remote diagnosis and more.



Integrated Robot Controller for SR4-560 & SR6-920



The integrated controllers for Dobot SR industrial robots are super compact products developed by DOBOT with strong performance, high quality at low cost. By adopting fully self-developed encoders, controllers and drivers, DOBOT reduced 80% of the controller's original size. Highly integrated with intensive power density, support remote diagnostics.

Technical Parameters

Model Number	DT-DB-SC161-00I	DT-DB-SC162-00I	
Controlled Axes	6 axes + external axes	6 axes + external axes	
Input Power	Single-phase 220V/230V AC, 15A, 50/60HZ	Single-phase 220V/230V AC, 30A, 50/60HZ	
Output Power	24V DC, 14.6A	24V DC, 14.6A	
Supported Motor Power (max.)	All joints:750W	J1: 1.5kW J2: 1.5kW J3: 1.5kW J4: 750W J5: 750W J6: 750W	
Braking Resistor	three, 80W, 80Ω	two, 200W, 50Ω	
Supported Encoder Type	Panasonic, TAMAGAWA, Nikon, Nidec, BISS-C		
Communication Interface	EtherCAT (for External Axes), Ethernet*2, RS232		
I/O Interface	28-Channel Ordinary Digital Input 6-Channel Digital Input for the Robot Manipulator 2-Channel Relay 17-Channel Ordinary Digital Output 4-Channel Digital Output for the Robot Manipulator		
Expanded Encoder	2-Channel Incremental Encoder		
Method of Teach & Playback	Hand-Held Teach Pendant/APP		
Programming Language	Lua		
Installment	Floor		
Environment	Temperature: 0°C ~45°C , Humidity: ≤ 95%, No Condensation		
Protection Rating	IP20		
Cooling Method	Forced-Air Cooling		
Safety Features	Emergency Stop Function		
Indicator	PWR: Power indicator, EN: Enable indicator, RUN: Indicator for programming running, ALM: Abnormal indicator		
Maintenance	Software Diagnostic Tool, Power-off Zero Save, Reserve Remote Service		



Integrated Robot Controller for SA3-400 & SA6-600





Model Number	SC240	SC241
Controlled Axes	4 Axes + External Expansion Axes	
Input Power	Single-Phase 220V/230 AC,10A,50/60Hz	Single-Phase 220V/230 AC,16A,50/60Hz
Output Power	DC24V	<i>I</i> ,2.5A
Supported Motor Power (max.)	J1:400W J2:400W J3:200W J4:100W	J1:750W J2:750W J3:400W J4:200W
Braking Resistor	100W	,20Ω
Supported Encoder Type	Panasonic, TAMAGAWA, Nikon, Nidec, BISS-C	
Communication Interface	EtherCAT (for External Axes), Ethernet*2, RS232	
I/O Interface	28-Channel Ordinary Digital Input 6-Channel Digital Input for the Robot Manipulator 2-Channel Relay 17-Channel Ordinary Digital Output 4-Channel Digital Output for the Robot Manipulator	
Expanded Encoder	2-Channel Incremental Encoder	
Method of Teach & Playback	Hand-Held Teach Pendant/APP	
Programming Language	Lua	
Installment	Floor	
Environment	Temperature: 0°C ${\sim}45^\circ\text{C}$, Humidity: ${\leqslant}$ 95%, No Condensation	
Protection Rating	IP20	
Cooling Method	Forced-Air Cooling	
Safety Features	Emergency Stop Function	
Indicator	PWR: Power indicator, EN: Enable indicator, RUN: Indicator for programming running, ALM: Abnormal indicator	
Maintenance	Software Diagnostic Tool, Power-off Zero Save, Reserve Remote Service	





Technical Parameters

Model Number	DT-CR-CC161-00I
Controlled Axes	6 Axes+External Expansion Axes
Input Power	Single Phase 110V/220V AC, 7.5A, 50/60HZ
Output Power	48V, 20A
Supported Motor Power (Max.)	-
Braking Resistors	Four, 17W, 10Ω
Supported Types of Encoders	-
Communication Interface	EtherCAT(for External Axes), Ethernet
I/O Interface	 16 Digital Outputs 16 Digital Inputs/Outputs (Multiplexing) 2 Analog Outputs (Voltage: 0V-10V, Current: 4mA-20mA) 2 Analog Inputs (Voltage: 0V-10V, Current: 4mA-20mA) 1 Incremental Encoder ABZ Input
Method of Teach & Playback	Hand-Held Teach Pendant/APP
Programming Language	Script/Blockly/Graphical Programming
Installment	Floor
Enviroment	Temperature: 0°C ~45°C, Humidity: ≤ 95%, No Condensation
Protection Rating	IP20
Cooling Method	Forced-Air Cooling
Safety Features	Emergency stop function, reserved external security interface that can be controlled by I/O interface
Indicator	The indicator light will be steady red when the power is on; the indicator light will be off when the power is off.
Maintenance	Diagnostic Software Tool, Power-off Zero Save, Reserve Remote Servic

О ООВОТ

Teach Pendant



Applicable to DOBOT SA & SR industrial robots. Support both button and touch control. User-friendly interface, innovative interactive programming, secondary development available and mechanical structure dynamic algorithms of various for various applications.

Electrical Specifications

Rated Power	< 8W
Rated Voltage	DC24V, working range DC 18V~32V
Power Protection	Power surge, lightning protection
Allowed Power- off Time	< 5ms
CE	Comply with EN61000-6-2:2005, EN61000-6-4:2007
RoHS	RoHS compliant with lightning surge ±4KV, group pulse ±4KV Static electricity 4KV, air discharge 8KV

Environment Requirements

Working Temperature	0°C ~50°C
Storage Temperature	-25°C ~60°C
Ambient Humidity	10~90%RH (no condensation)
Shock Resistance	10~25Hz (2G/30 minutes in X, Y, Z directions)
Cooling Method	natural air cooling

Other

Protection Rating	IP20 for the whole machine
Mechanical Structure	ABS
Machine Size	250 $ imes$ 160 $ imes$ 95 (mm) (without power terminal)
Machine Weight	Main body is about 900g, whole machine (including cable and wiring box) is 1600g

Hardware Specifications

Display Screen	7" TFT LCD
Resolution	800×480
Color	65536 color
Brightness	450 cd/m ²
Backlight	LED
LCD Lifespan	50000 Hours
Touch Screen	4-wire industrial resistance touch screen (surface hardness 4H)
CPU	32 Bit 400MHz RISC
Memory	128M Flash + 64M DDR2 DRAM
RTC	Built-in real-time clock
Ethernet	100M
USB Port	One USB Host 1.1 Port
Operating System	LINUX or WINDOWS CE optional
Buttons	A three-segment safety switch, a key switch A self-locking switch with light, a safety emergency stop switch 6 sets of 12 programmable silica gel (metal plate) buttons



Dobot SCStudio is an industrial robot programming platform, applicable to Dobot industrial robots including SA/SR/CR series. The software offers user-friendly interface and interactive programming, and supports secondary development. Dobot SCStudio provides a variety of mechanical structure kinematics algorithms and built-in virtual simulated environments, making it easier and faster to deploy various applications on site.

Features







Operating System Windows 7/10 (32/64 bit operating system)

Interactive Programming

- 1. Easy inserting command, no keyboard programming required.
- 2. Highlighted script, intelligent code completion and 3. display of command's comment.
- 3. Be able to set breakpoints. Single step execution, variable monitoring types.
- 4. Variousbuilt-indebuggingtools(serialport,TCP,Modbus).

Virtual Simulation

The software provides virtual simulation algorithm, no need for on-site debugging and making it possible to debug remotely and connect seamlessly.

Visual Application Configuration

Built-in palletizing, conveyor tracking, vision application and corresponding visual configuration interface. Requiring no complex code, complex applications can be set up in a short period of time. More applications will be launched in the future.

Independent Upgrade

With one click, the software can be updated on cloud for free, requiring no technical support and creating greater added value.



CUSTOMER CASE

Screw Driving in China

Automating screw driving is harder than meets the eye. Adjusting the torque is hard even for professionals. Equipped with force sensing, DOBOT CR5 can automatically determine whether the screw has been driven according to the preset torque and work with various electric screwdrivers, making it easier and more cost-effective to automate screw driving tasks.



Touch Screen Testing in India

Touch screen testing in smartphone production often requires repetitive manual work. With the right end tool, DOBOT M1 can emulate any multi-touch gesture on the touch screen, such as single tap, double tap, pinching, swiping and rotating, optimizing the testing process and enabling workers to focus on value-added tasks.



Polishing & Sanding in China

Polishing, buffing, and even sanding tasks require a specific, often delicate touch. Backed force sensing, DOBOT CR5 can sand and polish even curved and uneven surfaces with the right amount of force control. Besides, DOBOT CR5 makes it super easy to use for polishing/sanding – you can record the path with your hand, rather than recording every waypoint.

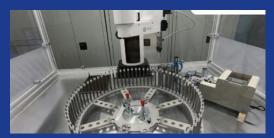


Pick & Place in South Korea

Robotic pick and place automation speeds up the process of picking parts up and placing them in new locations, increasing production rates. Compact and lightweight DOBOT M1 can be customized to fit specific production requirements including moving large, small, or hard-to-handle objects.

Loading & Unloading in Germany

Robotic machine loading automates the strenuous, repetitive task of supplying and placing or installing part(s) onto a machine in a safe environment. Programming the DOBOT M1 for loading or unloading is very easy and automatic load/unload systems increase production while at the same time creating an efficient, operator safe work.



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Vision-Based Sorting in Japan

Often mixed parts coming down a production line need to be sorted by some certain order. DOBOT M1 powered vision system can identify and sort randomly-placed objects on a conveyor according to location, color, shape or size, perfect for package inspection, reading barcodes, product assembly, defect reduction, and tracking and tracing.

PCB Pin Inserting in America

DOBOT high-speed PCB pin insertion robots are the technically and economically superior solution for your production. Thanks to their modular design, DOBOT offers manufacturers an ideal combination of flexibility and throughput for both high-mix and high-volume production environments.





Assembly in China

Robotic assembly processes provide the speed and precision manufacturers require without sacrificing quality and accuracy. The flexibility of DOBOT industrial robots allows manufacturers to optimize workflow, increase capacity, and easily produce a wider range of products.



Visit DOBOT's YouTube Channel

Scan this QR code or search "DOBOT industrial applications" playlist on YouTube.





GLOBAL SERVICE & SUPPORT

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With years of rapid development, Dobot has extended its service to more than 100 countries and regions around the world.





Technical Support

DOBOT provides step-by-step training to help our customers better understand and use DOBOT robots. The training includes but is not limited to equipment installation, robot expansion, upgrade and transformation, remote technical support, and so on.



After-Sales Service

DOBOT offers timely and professional service, including online support via phone or emails.



Request a Quote? Contact sales@dobot.cc Call +(86) 400 800 7266 to find a distributor near your location



Any Questions? Contact info@dobot.cc

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